1.	Record Nr.	UNINA9910452775803321
	Autore	Schwartzman Kathleen Crowley <1948->
	Titolo	The chicken trail [[electronic resource]] : following workers, migrants, and corporations across the Americas / / Kathleen C. Schwartzman
	Pubbl/distr/stampa	Ithaca, : ILR Press, 2013
	ISBN	0-8014-6804-3 0-8014-5116-7 0-8014-6805-1
	Descrizione fisica	1 online resource (225 p.)
	Disciplina	338.1/76500973
	Soggetti	Chicken industry - United States Chicken industry - Mexico Foreign workers, Mexican - United States Unemployment - United States Unemployment - Mexico Electronic books. United States Emigration and immigration Mexico Emigration and immigration United States Commerce Mexico Mexico Commerce United States
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
	Note generali	Bibliographic Level Mode of Issuance: Monograph
	Nota di bibliografia	Includes bibliographical references and index.
	Nota di contenuto	Why follow chickens? -- Ethnic succession in the south -- Where have all the workers gone? -- Taylorism invades the hen house -- Solving industry crises : pollos y polleros -- Squeezing out Mexican chicken -- Voice : squawking at globalization -- Exit Mexico : si muero lejos de ti -- The global dilemma : summary and reflections.
	Sommario/riassunto	In The Chicken Trail, Kathleen C. Schwartzman examines the impact of globalization-and of NAFTA in particular-on the North American poultry industry, focusing on the displacement of African American workers in the southeast United States and workers in Mexico. Schwartzman documents how the transformation of U.S. poultry production in the 1980's increased its export capacity and changed the

nature and consequences of labor conflict. She documents how globalization-and NAFTA in particular-forced Mexico to open its commodity and capital markets, and eliminate state support of corporations and rural smallholders. As a consequence, many Mexicans were forced to abandon their no longer sustainable small farms, with some seeking work in industrialized poultry factories north of the border. By following this chicken trail, Schwartzman breaks through the deadlocked immigration debate, highlighting the broader economic and political contexts of immigration flows. The narrative that undocumented worker take jobs that Americans don't want to do is too simplistic. Schwartzman argues instead that illegal immigration is better understood as a labor story in which the hiring of undocumented workers is part of a management response to the crises of profit making and labor-management conflict. By placing the poultry industry at the center of a constellation of competing individual, corporate, and national interests and such factors as national debt, free trade, economic development, industrial restructuring, and African American unemployment, The Chicken Trail makes a significant contribution to our understanding of the implications of globalization for labor and how the externalities of free trade and neoliberalism become the social problems of nations and the tragedies of individuals.

2. **Record Nr.**   UNINA9910639197403321

Autore	Parrinello, Sandro
Titolo	Disegnare il paesaggio : esperienze di analisi e letture grafiche dei luoghi : appunti per la didattica / Sandro Parrinello
Pubbl/distr/stampa	Firenze, : Edifir Edizioni Firenze, 2013
ISBN	978-88-7970-617-9
Descrizione fisica	303 p. : ill. ; 26 cm
Collana	Disegno, rilievo e progettazione
Locazione	FARBC
Collocazione	URB.LE B 3417
Lingua di pubblicazione	Italiano
Formato	Materiale a stampa
Livello bibliografico	Monografia

3. **Record Nr.**   UNINA9910418353203321

Autore	Taha Walid <1972->
Titolo	Cyber-physical systems : a model-based approach / / Walid M. Taha, Abd-Elhamid M. Taha, Johan Thunberg
Pubbl/distr/stampa	Springer Nature, 2021
	Cham, Switzerland : , : Springer Nature Switzerland AG : , : imprint : Springer, , [2021] ©2021
ISBN	3-030-36071-7
Descrizione fisica	1 online resource (xxii, 187 pages) : illustrations; digital, PDF file(s)
Disciplina	004.6
Soggetti	Computer organization
	Computer engineering
	Internet of things
	Embedded computer systems
	Computer simulation
	Control engineering
	Robotics
	Mechatronics
	Computer Systems Organization and Communication Networks
	Cyber-physical systems, IoT

	Simulation and Modeling Control, Robotics, Mechatronics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Part I: Core Concepts -- 1. What is a Cyber-Physical System? -- 2. Modeling Physical Systems -- 3. Hybrid Systems -- 4. Control Theory -- 5. Modeling Computational Systems -- 6. Coordinate Transformation (Robot Arm) -- Part II: Selected Topics -- 7. Game Theory -- 8. Communications -- 9. Sensing and Actuation -- Part III: Appendix -- A. Acumen Reference Manual -- Index.
Sommario/riassunto	In this concise yet comprehensive Open Access textbook, future inventors are introduced to the key concepts of Cyber-Physical Systems (CPS). Using modeling as a way to develop deeper understanding of the computational and physical components of these systems, one can express new designs in a way that facilitates their simulation, visualization, and analysis. Concepts are introduced in a cross-disciplinary way. Leveraging hybrid (continuous/discrete) systems as a unifying framework and Acumen as a modeling environment, the book bridges the conceptual gap in modeling skills needed for physical systems on the one hand and computational systems on the other. In doing so, the book gives the reader the modeling and design skills they need to build smart, IT-enabled products. Starting with a look at various examples and characteristics of Cyber-Physical Systems, the book progresses to explain how the area brings together several previously distinct ones such as Embedded Systems, Control Theory, and Mechatronics. Featuring a simulation-based project that focuses on a robotics problem (how to design a robot that can play ping-pong) as a useful example of a CPS domain, Cyber-Physical Systems: A Model-Based Approach demonstrates the intimate coupling between cyber and physical components, and how designing robots reveals several non-trivial control problems, significant embedded and real-time computation requirements, and a need to consider issues of communication and preconceptions.