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Ubiquitous Brooks-Iyengars Robust Distributed Real-time Sensing Algorithm: Past, Present and Future -- Index.

Sommario/riassunto

This book provides a comprehensive analysis of Brooks-Iyengar Distributed Sensing Algorithm, which brings together the power of Byzantine Agreement and sensor fusion in building a fault-tolerant distributed sensor network. The authors analyze its long-term impacts, advances, and future prospects. The book starts by discussing the Brooks-Iyengar algorithm, which has made significant impact since its initial publication in 1996. The authors show how the technique has been applied in many domains such as software reliability, distributed systems and OS development, etc. The book exemplifies how the algorithm has enhanced new real-time features by adding fault-tolerant capabilities for many applications. The authors posit that the Brooks-Iyengar Algorithm will to continue to be used where fault-tolerant solutions are needed in redundancy system scenarios. Provides a comprehensive investigation of Brooks-Iyengar Algorithm and the recently developed methods based on this algorithm; Specifies the importance and position of theoretical methods in dealing with real-world problems in the context of distributed sensing; Presents basics and mathematical foundations needed to analyze Brooks-Iyengar Algorithm.