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| Autore                  | Um Jung-Sup  |
| Titolo                  | Drones as Cyber-Physical Systems [[electronic resource] ] : Concepts and Applications for the Fourth Industrial Revolution / / by Jung-Sup Um  |
| Pubbl/distr/stampa      | Singapore : , : Springer Singapore : , : Imprint : Springer, , 2019  |
| ISBN                    | 981-13-3741-1  |
| Edizione                | [1st ed. 2019.]  |
| Descrizione fisica      | 1 online resource (XIII, 274 p. 63 illus., 50 illus. in color.)  |
| Disciplina              | 621.382  |
| Soggetti                | Electrical engineering<br>Geographical information systems<br>Computer organization<br>Geophysics<br>Communications Engineering, Networks<br>Geographical Information Systems/Cartography<br>Computer Systems Organization and Communication Networks<br>Geophysics and Environmental Physics  |
| Lingua di pubblicazione | Inglese  |
| Formato                 | Materiale a stampa   |
| Livello bibliografico   | Monografia   |
| Nota di contenuto       | Chapter 1. Introduction to the 4th industrial revolution -- Chapter 2. Drone flight ready -- Chapter 3. Cyber systems -- Chapter 4. Physical systems -- Chapter 5. Location sensors -- Chapter 6. Imaging sensors -- Chapter 7. Valuing cyber-physical bridging intensity of drone -- Chapter 8. Futurology and future prospect of drone CPS.  |
| Sommario/riassunto      | This book introduces the concept of using drones as a teaching tool to explore the fundamental principles, technology and applications of Cyber-Physical Systems (CPS). A short introduction sets CPS in the context of the 4th industrial revolution, and describes various CPS technologies including self-driving cars, commercial intelligent drones and mobile robots, in which artificial intelligence routinely supports smarter decision-making. The core of the book then focuses on commercially available drones, the only available system offering the advantage of cyber-physical bridging through 3D autonomous dynamic flying in classroom conditions. Chapters describe drone technology, |

including location sensors and imaging systems. CPS theory is explained through typical drone flying procedures and do-it-yourself (DIY) aerial photography in which communication between sensors, actuators and controllers occurs through cyber-physical bi-directional bridging. This book opens new possibilities in fostering 4th industrial revolution literacy, introducing relevant examples from readily available equipment, making core elements of cyber-physical bridging accessible. It is aimed primarily at those students who have an interest in CPS, drones and those from disciplines that are concerned with spatial information.

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