1. Record Nr. UNINA9910808835303321

Autore	Wylie Alex
Titolo	Geoffrey Hill's later work : radiance of apprehension / / Alex Wylie
Pubbl/distr/stampa	Manchester, UK : , : Manchester University Press, , 2019 ©2019
ISBN	1-5261-2496-3 1-5261-5035-2 1-5261-2495-5
Descrizione fisica	1 online resource (188 pages) : digital file(s)
Collana	Manchester scholarship online
Disciplina	821.912
Soggetti	English poetry - History and criticism Literature Literary Studies: Poetry & Poets LITERARY CRITICISM / Poetry
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Previously issued in print: 2019.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	'A theory of energy' -- A postscript on modernist poetics? -- 'Turbulently at rest' : order and anarchy in the later work -- 'There are no demons' : faith and metaphysical desire -- 'Bless hierarchy' : the cultural politics of Hill's later work -- 'A calling for England' : Hill and the political imagination.
Sommario/riassunto	This title provides an exploration of the later work of Geoffrey Hill, often described as 'the greatest living poet' in his lifetime. This book reads, interprets, evaluates, and sets in context the work of Hill's prolific later period from 1996 to 2016, the year of his death.

2. Record Nr. UNINA9910347047103321

Autore	Puls Stephan
Titolo	Situationsverstehen fur die Risikobeurteilung bei der Mensch-Roboter-Kooperation
Pubbl/distr/stampa	KIT Scientific Publishing, 2014
ISBN	1000044584
Descrizione fisica	1 online resource (XII, 169 p. p.)
Lingua di pubblicazione	Tedesco
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	In the proposed system the environment of an industrial robot is captured through algorithms of machine learning. Thus, objects and human actions are determined. Based on semantic analysis situational knowledge is inferred and dynamic risk assessment as well as robotic behaviour are concluded. Consequently, this provides the foundation for a reactive robot system for achieving efficient and safe human-robot-cooperation.