

1. Record Nr.	UNINA9910346948303321
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Titolo	Prädiktive Lichtfunktionen für volladaptive Scheinwerfersysteme
Pubbl/distr/stampa	KIT Scientific Publishing, 2019
ISBN	1000088261
Descrizione fisica	1 electronic resource (VII, 215 p. p.)
Collana	Spektrum der Lichttechnik / Karlsruher Institut für Technologie (KIT), Lichttechnisches Institut
Lingua di pubblicazione	Tedesco
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	In this work, the realisation of an adaptive driving beam is examined that is based on the motion prediction of the ego vehicle and other traffic participants. Furthermore, light functions are developed and analysed regarding their effectiveness that project situation adaptive recommendations for action in front of the vehicle regarding a turn or lane change intention of the driver.