Record Nr. UNINA9910346782303321 Autore Schönbein Miriam Titolo Omnidirectional Stereo Vision for Autonomous Vehicles KIT Scientific Publishing, 2014 Pubbl/distr/stampa **ISBN** 1000046298 Descrizione fisica 1 online resource (XV, 125 p. p.) Schriftenreihe / Institut für Mess- und Regelungstechnik, Karlsruher Collana Institut für Technologie Technology: general issues Soggetti Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Sommario/riassunto Environment perception with cameras is an important requirement for many applications for autonomous vehicles and robots. This work presents a stereoscopic omnidirectional camera system for autonomous vehicles which resolves the problem of a limited field of view and provides a 360° panoramic view of the environment. We present a new projection model for these cameras and show that the camera setup overcomes major drawbacks of traditional perspective cameras in many applications.