

1. Record Nr.	UNINA9910346769703321
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Titolo	Ein Beitrag zur viskoelastischen Modellierung nichtholonomer Bindungsgleichungen
Pubbl/distr/stampa	KIT Scientific Publishing, 2017
ISBN	1000056152
Descrizione fisica	1 electronic resource (XVIII, 216 p. p.)
Collana	Schriftenreihe des Instituts für Technische Mechanik, Karlsruher Institut für Technologie
Lingua di pubblicazione	Tedesco
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	Based on a formalism to simulate mechanical rigid body systems with plane frictional contacts, an extension to systems with rolling contacts is proposed. A special focus is put on tangential contact compliance. A mathematical convergency proof of the solution of the tangential elastic formulation to the rigid one is proposed.