Record Nr.	UNINA9910339014603321
Autore	Aström Karl Johan
Titolo	Feedback Systems : An Introduction for Scientists and Engineers / / Richard M. Murray, Karl Johan Aström
Pubbl/distr/stampa	Princeton, NJ : , : Princeton University Press, , [2010] ©2008
ISBN	1-282-60796-0 9786612607967 1-4008-2873-2
Descrizione fisica	1 online resource (409 p.)
Classificazione	SK 880
Disciplina	629.8/3 629.83
Soggetti	Feedback control systems
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references (pages [377]-385) and index.
Nota di contenuto	Frontmatter Contents Preface / Åström, Karl Johan / Murray, Richard M Chapter One. Introduction Chapter Two. System Modeling Chapter Three. Examples Chapter Four. Dynamic Behavior Chapter Five. Linear Systems Chapter Six. State Feedback Chapter Seven. Output Feedback Chapter Eight. Transfer Functions Chapter Nine. Frequency Domain Analysis Chapter Ten. PID Control Chapter Eleven. Frequency Domain Design Chapter Twelve. Robust Performance Bibliography Index
Sommario/riassunto	This book provides an introduction to the mathematics needed to model, analyze, and design feedback systems. It is an ideal textbook for undergraduate and graduate students, and is indispensable for researchers seeking a self-contained reference on control theory. Unlike most books on the subject, Feedback Systems develops transfer functions through the exponential response of a system, and is accessible across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability

1.

of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. They provide exercises at the end of every chapter, and an accompanying electronic solutions manual is available. Feedback Systems is a complete one-volume resource for students and researchers in mathematics, engineering, and the sciences. Covers the mathematics needed to model, analyze, and design feedback systems Serves as an introductory textbook for students and a self-contained resource for researchers Includes exercises at the end of every chapter Features an electronic solutions manual Offers techniques applicable across a range of disciplines