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Titolo	Handbook of Contact Mechanics : Exact Solutions of Axisymmetric Contact Problems / / by Valentin L. Popov, Markus Heß, Emanuel Willert
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Soggetti	Mechanics, Applied Solids Mechanics Engineering mathematics Engineering - Data processing Solid Mechanics Classical Mechanics Mathematical and Computational Engineering Applications
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Nota di contenuto	Introduction -- Normal contact without adhesion -- Normal contact with adhesion -- Tangential contact -- Torsional contact -- Wear -- Transversely isotropic problems -- Viscoelastic materials -- Contact problems of functionally graded materials -- Annular contacts -- Appendix -- Index.
Sommario/riassunto	This open access book contains a structured collection of complete solutions of all significant axially symmetric contact problems. It provides solutions for classical profiles such as the sphere, cone or flat cylindrical punch as well as a multitude of other technically relevant shapes, e.g. the truncated cone, the worn sphere, rough profiles, hollow cylinders, etc. Normal, tangential and torsional contacts with and without adhesion are examined. Elastically isotropic, transversally isotropic, viscoelastic and functionally graded media are addressed. The solutions of the contact problems cover the relationships between the macroscopic quantities of force and displacement, the contact

configuration as well as the stress and displacement fields at the surface and in some cases within the half-space medium. The solutions are obtained by the simplest available method – usually involving the method of dimensionality reduction or approaches of reduction to the non-adhesive normal contact problem. The target audiences This book is geared towards engineers working in e.g. mechanical engineering, the tire industry, the automotive industry, polymer- and elastomer manufacturing. Additionally, it functions as a reference work for research and teaching.

Prof. Dr. rer. nat. Valentin L. Popov studied physics and obtained his doctorate in 1985 from the Lomonosov Moscow State University. He habilitated 1994 at the Institute of Strength Physics and Materials Science of the Russian Academy of Sciences. Since 2002 he has headed the Chair of System Dynamics and Friction Physics in the Institute of Mechanics at TU Berlin.

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