

1. Record Nr.	UNINA9910300431503321
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Titolo	Semi-Autonomous Networks : Effective Control of Networked Systems through Protocols, Design, and Modeling // by Airlie Chapman
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2015
ISBN	3-319-15010-3
Edizione	[1st ed. 2015.]
Descrizione fisica	1 online resource (207 p.)
Collana	Springer Theses, Recognizing Outstanding Ph.D. Research, , 2190-5053
Disciplina	629.895630151563
Soggetti	Physics Automatic control Applications of Graph Theory and Complex Networks Control and Systems Theory
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	"Doctoral Thesis accepted by University of Washington."
Nota di bibliografia	Includes bibliographical references at the end of each chapters and index.
Nota di contenuto	Nomenclature -- Acknowledgments -- Dedication -- Supervisor's Foreword -- Introduction -- Preliminaries -- Notation -- Network Topology -- Consensus Dynamics -- Advection on Graphs -- Beyond Linear Protocols -- Measures and Rewiring -- Distributed Online Topology Design for Disturbance Rejection -- Network Topology Design for UAV Swarming with Wind Gusts -- Cartesian Products of Z-Matrix Networks: Factorization and Interval Analysis -- On the Controllability and Observability of Cartesian Product Networks -- Strong Structural Controllability of Networked Dynamics -- Security and Infiltration of Networks: A Structural Controllability and Observability Perspective -- Conclusion and Future Work -- Appendix -- Single Anchor State Measures.
Sommario/riassunto	This thesis analyzes and explores the design of controlled networked dynamic systems - dubbed semi-autonomous networks. The work approaches the problem of effective control of semi-autonomous networks from three fronts: protocols which are run on individual agents in the network; the network interconnection topology design; and efficient modeling of these often large-scale networks. The author

extended the popular consensus protocol to advection and nonlinear consensus. The network redesign algorithms are supported by a game-theoretic and an online learning regret analysis.
