1. Record Nr. UNINA9910299869203321 Autore Dey Rajeeb Titolo Stability and Stabilization of Linear and Fuzzy Time-Delay Systems: A Linear Matrix Inequality Approach / / by Rajeeb Dey, Goshaidas Ray, Valentina Emilia Balas Cham:,: Springer International Publishing:,: Imprint: Springer,, Pubbl/distr/stampa 2018 3-319-70149-5 **ISBN** Edizione [1st ed. 2018.] 1 online resource (XX, 267 p. 43 illus.) Descrizione fisica Collana Intelligent Systems Reference Library, , 1868-4394;; 141 003.74 Disciplina Soggetti Computational intelligence Artificial intelligence Control engineering Computational Intelligence Artificial Intelligence Control and Systems Theory Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Nota di bibliografia Includes bibliographical references. This book provides a clear understanding in formulating stability Sommario/riassunto analysis and state feedback control of retarded time delay systems using Lyapunov's second method in an LMI framework. The chapters offer a clear overview of the evolution of stability analysis in terms of the construction of a Lyapunov functional and use of the integral inequalities in order to reduce the gap of delay upper bound estimate compared to frequency domain method through existing and proposed stability theorems. Power system engineering problem has been presented here to give readers fair idea on applicability of the model

and method for solving engineering problems. Without deviating from the framework of analysis more complex dynamics of the system have been dealt with here that includes actuator saturation and thereby ascertaining local stability for an estimated time-delay and domain of attraction. Nonlinearity in a time-delay system has been dealt with in the T-S fuzzy modeling approach. This book is useful as a textbook for

Master's students and advanced researcher working in the field of control system engineering, and for practicing engineers dealing with such complex dynamical systems. The strengths of the book are lucidity of presentation, lucidity of solution method, MATLAB programs given in the appendix that help the novice researcher to carry out research in this area independently, clear idea about the formulation of desired stability and control problem in a LMI framework, application problem provided can motivate students and researcher to recast their problems in the similar framework easily, helpful for readers to use the stability (stabilization) conditions or formulate their own stability conditions easily for a complicated linear or nonlinear dynamical system.