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Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references at the end of each chapters.
Nota di contenuto	Modeling and Identification of the Human-exoskeleton Interaction Dynamics for Upper Limb Rehabilitation -- Motion Planning Algorithm Based on Environmental Information for Mars Rover -- Fluctuation Analysis of Runoff Time Series Under Coarse Graining Network Modeling Method -- Design and implementation of an intelligent cooking robot based on Internet of things.
Sommario/riassunto	Proceedings of the 2015 Chinese Intelligent Automation Conference presents selected research papers from the CIAC'15, held in Fuzhou, China. The topics include adaptive control, fuzzy control, neural network based control, knowledge based control, hybrid intelligent control, learning control, evolutionary mechanism based control, multi-sensor integration, failure diagnosis, reconfigurable control, etc. Engineers and researchers from academia, industry and the government can gain valuable insights into interdisciplinary solutions in the field of intelligent automation.

