

1. Record Nr.	UNINA9910299733703321
Titolo	New Trends in Medical and Service Robots : Challenges and Solutions / / edited by Aleksandar Rodi, Doina Pisla, Hannes Bleuler
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2014
ISBN	3-319-05431-7
Edizione	[1st ed. 2014.]
Descrizione fisica	1 online resource (379 p.)
Collana	Mechanisms and Machine Science, , 2211-0984 ; ; 20
Disciplina	610.28
Soggetti	Robotics Automation Biomedical engineering Mechanical engineering Robotics and Automation Biomedical Engineering and Bioengineering Mechanical Engineering
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references at the end of each chapters.
Nota di contenuto	Preface -- Robotic Assistance for Senior People for Safe Mobility and Work Support, by D. Eck, F. Leutert, K. Schilling -- The Robot that Learns from the Therapist how to Assist Stroke Patients, by M.D. Kostic, M.D. Popovic, D.B. Popovic -- Lower Limbs Robotic Rehabilitation: A case study with clinical trials, by M. Bouri, E. Abdi, H. Bleuler, F. Reynard and O. Deriaz -- Robot-Assisted 3D Medical Sonography, by P.B. Petrovic, N. Lukic and I. Danilov -- Innovative Approaches Regarding Robots for Brachytherapy, by D. Pisla, N. Plitea, B. Galdau, C. Vaida, B. Gherman -- Markerless Vision-Based Skeleton Tracking in Therapy of Gross Motor Skill Disorders in Children, by B. Karan, S. Golubovic, M. Gnjatovic -- Force Training for Position/Force Control of Massage Robots, by V. Golovin, M. Arkhipov, V. Zhuravlev -- Flexible Bi-Modal Control Modes for Hands-Free Operation of a Wheelchair by Head Movements and Facial Expressions, by E.J. Rechy-Ramirez and H. Hu -- New Results On Classifying EMG Signals for Interfacing Patients and Mechanical Devices, by G. Gini, L. Cavazzana,

F. Mutti, P. Belluco, A. Mauri -- Mathematical Modelling of Human Affective Behavior Aimed to Development Robot EI-Controller, by A. Rodi, K. Addi -- Robot Skill Acquisition by Demonstration and Explorative Learning, by B. Nemeč, A. Ude -- Two Faces of Human-Robot Interaction: Field and Service Robots, by R. Ventura -- Advanced Gesture and Pose Recognition Algorithms using Computational Intelligence and Microsoft KINECT Sensor, by D. Kati, P. Radulovi, S. Spasojevi, Ž. urovi, A. Rodi -- Recursive Design of Dependable Robot Systems for Safety-Critical Applications, by A. Wagner -- Some Applications of Biomimetics and Fractional Calculus in Control and Modeling of (Bio)robotic Systems M.Lazarevi -- Towards Sensor-Less Haptic Teleoperation, by A. Hacı, M. Franc -- Incorporation of Artificial Limbs and Role of Haptic Feedback, by A. Sengul, S. Shokur, H. Bleuler -- Offline Imitation of a Human Motion by a Humanoid Robot Under Balance Constraint, by K. Munirathinam, C. Chevallereau, S. Sakka -- Contributions on the Modeling and Simulation of the Human Knee Joint with Applications to the Robotic Structures, by D. Tarnita, M. Catana, D. N. Tarnita -- How to Control Anthropomorphic Robot – Engineering and Cognitive Approach, by V. Potkonjak, K. Jovanovic and P. Milosavljevic -- Kinematic and Dynamic Modeling of a Parallel Manipulator with Eight Actuation Modes, by S. Caro, D. Chablat, P. Wenger and X. Kong -- Experiences on Service Robots at LARM in Cassino, by M. Ceccarelli, G. Carbone -- Moving from ‘How to Go There?’ to ‘Where to Go?’: Towards Increased Autonomy of Mobile Robots, by F. Amigoni, N. Basilico, A. Quattrini Li -- Safety for an Autonomous Bucket Excavator During Typical Landscaping Tasks, by G. Zolynski, D. Schmidt, and K. Berns -- Testing Capacity for Space Technology Suppliers, by A. Pisla, C.Vaida.

Sommario/riassunto

This volume describes new frontiers in medical and service robotics in the light of recent developments in technology to advance robot design and implementation. In particular, the work looks at advances in design, development and implementation of contemporary surgical, rehabilitation and biorobots. Surgical robots allow surgeons greater access to areas under operation using more precise and less invasive methods. Rehabilitation robots facilitate and support the lives of the infirm, elderly people, or those with dysfunction of body parts affecting movement. These robots are also used for rehabilitation and related procedures, such as training and therapy. Biorobots are designed to imitate the cognition of humans and animals. The need to substitute humans working on delicate, tiresome and monotonous tasks, or working with potentially health-damaging toxic materials, requires intelligent, high-performance service robots with the ability to cooperate, advanced communication and sophisticated perception and cognitive capabilities. Progress in this field is fast and results need to be disseminated to stimulate both practical applications and further research. Thus, these papers are a valuable addition to existing literature.
