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Titolo	Embedded Platforms for UAS Landing Path and Obstacle Detection : Integration and Development of Unmanned Aircraft Systems // by Umberto Papa
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Collana	Studies in Systems, Decision and Control, , 2198-4182 ; ; 136
Disciplina	623.7469
Soggetti	Computational intelligence Electronics Microelectronics Aerospace engineering Astronautics Artificial intelligence Space sciences Computational Intelligence Electronics and Microelectronics, Instrumentation Aerospace Technology and Astronautics Artificial Intelligence Space Sciences (including Extraterrestrial Physics, Space Exploration and Astronautics)
Lingua di pubblicazione	Inglese
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Nota di bibliografia	Includes bibliographical references.
Nota di contenuto	Introduction to Unmanned Aircraft Systems (UAS) -- Sonar Sensor Model for Safe Landing -- Atmosphere effects on the SRS -- Integration among Ultrasonic and Infrared sensors -- UAS safe landing using an optical sensor -- UAS endurance enhancement -- Conclusions.
Sommario/riassunto	This book reports on the design and development of a system that assists remote pilots during the landing procedure. In particular, it covers a previously neglected topic, namely the search for the best pathway and landing site. It describes the system's components, such

as the ultrasonic sensor, infrared sensor and optical sensor, in detail, and discusses the experimental tests carried out in both controlled laboratory and real-world environments. Providing a fascinating survey of the state of the art in the field of unmanned aircraft system electronics design and development, the book also presents recent advances in and cutting-edge methodologies for the development of acquisition systems and inexpensive sensor design for navigation data.
