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Nota di contenuto	Multiagent Systems Under Uncertainty -- The Decentralized POMDP Framework -- Finite-Horizon Dec-POMDPs -- Exact Finite-Horizon Planning Methods -- Approximate and Heuristic Finite-Horizon Planning Methods -- Infinite-Horizon Dec-POMDPs -- Infinite-Horizon Planning Methods: Discounted Cumulative Reward -- Infinite-Horizon Planning Methods: Average Reward -- Further Topics.
Sommario/riassunto	This book introduces multiagent planning under uncertainty as formalized by decentralized partially observable Markov decision processes (Dec-POMDPs). The intended audience is researchers and graduate students working in the fields of artificial intelligence related to sequential decision making: reinforcement learning, decision-theoretic planning for single agents, classical multiagent planning, decentralized control, and operations research. .

