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Nota di bibliografia	Includes bibliographical references at the end of each chapters and index.
Nota di contenuto	Aerial Robots 1 -- Actuation -- Grasping 1 -- Manipulation -- Human-Robot Interaction 1 -- Mobile Robots 1 -- Perception -- Aerial Robots 2 -- Grasping 2 -- Planning and Control -- Mobile Robots -- Human-Robot Interaction 2.
Sommario/riassunto	Experimental Robotics XV is the collection of papers presented at the International Symposium on Experimental Robotics, Roppongi, Tokyo, Japan on October 3-6, 2016. 73 scientific papers were selected and presented after peer review. The papers span a broad range of sub-fields in robotics including aerial robots, mobile robots, actuation, grasping, manipulation, planning and control and human-robot interaction, but shared cutting-edge approaches and paradigms to experimental robotics. The readers will find a breadth of new directions of experimental robotics. The International Symposium on Experimental Robotics is a series of bi-annual symposia sponsored by the International Foundation of Robotics Research, whose goal is to provide a forum dedicated to experimental robotics research. Robotics

has been widening its scientific scope, deepening its methodologies and expanding its applications. However, the significance of experiments remains and will remain at the center of the discipline. The ISER gatherings are a venue where scientists can gather and talk about robotics based on this central tenet. .
