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Nota di bibliografia	Includes bibliographical references at the end of each chapters.
Nota di contenuto	Observer Design for Discrete-time Switched Lipschitz Nonlinear Singular Systems with Time Delays and Unknown Inputs -- Research on grasping planning for apple picking robot's end-effector -- Region-based shape control for multi-robot systems with uncertain kinematics and dynamics -- Location and Navigation Study of Laser Base Station.
Sommario/riassunto	This book presents selected research papers from the 2015 Chinese Intelligent Systems Conference (CISC'15), held in Yangzhou, China. The topics covered include multi-agent systems, evolutionary computation, artificial intelligence, complex systems, computation intelligence and soft computing, intelligent control, advanced control technology, robotics and applications, intelligent information processing, iterative learning control, and machine learning. Engineers and researchers from academia, industry and the government can gain valuable insights into solutions combining ideas from multiple disciplines in the field of intelligent systems.

