1. | | |
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   | Record Nr. | UNINA9910207955403321 |
   | Autore | Jhering, Rudolf : von |
   | Titolo | Lo scopo nel diritto / Rudolf von Jhering ; traduzione e cura di Mario G. Losano |
   | Pubbl/distr/stampa | Torino : Aragno, 2014- |
   | Descrizione fisica | v. ; 24 cm |
   | Collana | Biblioteca Aragno |
   | Disciplina | 340.1 |
   | Locazione | FGBC |
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   | Lingua di pubblicazione | Italiano |
   | Formato | Materiale a stampa |
   | Livello bibliografico | Monografia |

2. | | |
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   | Record Nr. | UNINA9910454093903321 |
   | Titolo | Theory and algorithms for cooperative systems [[electronic resource] /] / editors, Don Grundel, Robert Murphey, Panos M. Pardalos |
   | Pubbl/distr/stampa | River Edge, NJ, : World Scientific, c2004 |
   | ISBN | 1-281-95598-1
 9786611955984
 981-279-659-2 |
   | Descrizione fisica | 1 online resource (604 p.) |
   | Collana | Series on computers and operations research ; ; 4 |
   | Altri autori (Persone) | GrundelDon
 MurpheyRobert
 PardalosP. M <1954-> (Panos M.) |
   | Disciplina | 006.3 |
   | Soggetti | Control theory
 Decision making - Mathematical models
 Cooperation - Mathematical models
 Mathematical optimization
 Electronic books. |
   | Lingua di pubblicazione | Inglese |

Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Papers presented at the Fourth Annual Conference on Cooperative Control and Optimization, held in Destin, Florida, November 2003.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Contents ; Preface ; 1 Mesh Stability in Formation of Distributed Systems ; 1 Introduction ; 2 String Stability of an Interconnection ; 3 Decomposition Technique ; 4 Spatial and Temporal Coordinations ; 5 System of Lyapunov Systems ; 6 Illustration ; 7 Conclusions and Future Work References 2 Designing the Control of a UAV Fleet with Model Checking ; 1 Introduction ; 2 Modeling the Game ; 3 Generating Search Strategies ; 4 Performance ; 5 Conclusions and Future Work ; References ; 3 Applying Simulated Annealing to the Multidimensional Assignment Problem 1 Introduction 2 The Algorithm ; 3 Design of Experiments ; 4 Results ; 5 Conclusions ; 6 Future Work ; References ; 4 On the Performance of Heuristics for Broadcast Scheduling ; 1 Introduction ; 2 The Broadcast Scheduling Problem ; 3 Heuristics ; 4 Computational Results 5 Conclusion References ; 5 Natural Language Processing in Control of Unmanned Aerial Vehicles ; 1 Introduction ; 2 Overview of Example Implementation ; 3 Detailed Description ; 4 Results ; 5 Future Work ; References ; Appendix: Examples of Parsed Outputs 6 Lyapunov-Based Partial Stabilization of a Nonholonomic UAV Model With Polytopic Input Constraints 1 Introduction ; 2 Control Lyapunov Functions ; 3 Removing Redundancy and Vertex Enumeration ; 4 Parameterizing S ; 5 Optimizing the Weighting Vector ; 6 Unicycle Model System 7 Discussion and Conclusion
Sommario/riassunto	Over the past several years, cooperative control and optimization have increasingly played a larger and more important role in many aspects of military sciences, biology, communications, robotics, and decision making. At the same time, cooperative systems are notoriously difficult to model, analyze, and solve - while intuitively understood, they are not axiomatically defined in any commonly accepted manner. The works in this volume provide outstanding insights into this very complex area of research. They are the result of invited papers and selected presentations at the <i>Fourth Annual Conf