Record Nr. UNINA9910166634803321 Autore Pyrhonen Juha Titolo Electrical machine drives control: an introduction // Juha Pyrhonen, Valeria Hrabovcova, R. Scott Semken Pubbl/distr/stampa Chichester, West Sussex, England:,: Wiley,, 2016 ©2016 **ISBN** 1-119-26040-X 1-119-26044-2 1-119-26047-7 Descrizione fisica 1 online resource (527 p.) Disciplina 621.46 Soggetti Electric driving Electric motors - Electronic control Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Note generali Description based upon print version of record. Nota di bibliografia Includes bibliographical references at the end of each chapters and index. Electrical Machine Drives Control: An Introduction; Contents; Preface; Nota di contenuto Abbreviations and Symbols; 1: Introduction to electrical machine drives control; 1.1 What is an electrical machine drive?; 1.2 Controlled variable speed drives: 1.2.1 DC variable speed drives: 1.2.2 AC variable speed drives; 1.3 Electrical machine drive implementation; 1.4 Controlled electrical drives and energy efficiency; 1.5 The electrical drive as an element of a controlled industrial process; References; 2: Aspects common to all controlled electrical machine drive types 2.1 Pulse width modulation converter electrical motor drive2.2 Converter interface to power source; 2.3 Fundamental mechanics; 2.4 Basic mechanical load types; 2.5 Proportional-integral-derivative controller in electrical drives; 2.6 The speed, torque, or position control of an electrical drive; 2.7 Control time rates and embedded system principles; 2.8 Per-unit values; 3: The fundamentals of electric machines; 3.1 Energy conversion in electric machines; 3.2 Industrial machine windings: 3.3 Effective winding turns and spatial harmonics: 3.4 Induction machine rotors; 3.5 The damper winding

3.6 AC winding systems 3.7 DC machine windings; 3.8 The brushless DC machine; 3.9 The magnetic circuit of an electric machine; 3.10

Motor voltage, flux linkage, flux, field weakening, and voltage reserve; 3.11 Motors in power-electronic electrical drives; References; 4: The fundamentals of space-vector theory; 4.1 Introduction to the space vector for current linkage; 4.1.1 Mathematical representation of the space vector; 4.1.2 Two-axis representation of the space vector; 4.1.3 Coordinate transformation of the space vector; 4.2 Space-vector equivalent circuits and the voltage-vector equations

- 4.3 Space-vector model in the general reference frame 4.4 The two-axis model; 4.5 Application of space-vector theory; References; 5: Torque and force production and power; 5.1 The Lorentz force; 5.2 The general equation for torque; 5.3 Power; 5.4 Reluctance torque and coenergy; 5.5 Reluctance torque and the cross-field principle in a rotating field machine; 5.6 Maxwell's stress tensor in the definition of torque; References; 6: Basic control principles for electric machines; 6.1 The control of a DC machine; 6.2 AC machine control basics; 6.3 Vector control of AC motors
- 6.4 Direct flux-linkage control and direct torque control6.4.1 The basis of direct torque control; 6.4.2 DFLC implementation; 6.4.3 Shortcomings of direct flux-linkage control; 6.5 Improving DFLC to achieve DTC; 6.5.1 Current model correction; 6.5.2 Stator flux-linkage eccentricity correction; 6.6 Other control principles; References; 7: DC and AC power electronic topologies modulation for the control of rotating-field motors; 7.1 The thyristor bridge as a power-electronic drive component; 7.2 The cycloconverter; 7.3 The load commutated inverter drive

7.4 Voltage source inverter power stages