1. Record Nr. UNIPARTHENOPE000030447

Autore	Cicotti, Giuseppe
Titolo	Service Quality Monitoring, Prediction And Refinement-Based Guarantee For Dynamic Service-Centric Systems / tesi di dottorato di: Giuseppe Cicotti ; tutor: Luigi Coppolino [risorsa elettronica]
Pubbl/distr/stampa	Napoli, 2014
Titolo uniforme	Service Quality Monitoring, Prediction And Refinement-Based Guarantee For Dynamic Service-Centric Systems
Descrizione fisica	1 disco ottico (CD-ROM) ; 12 cm
Disciplina	004.65
Collocazione	TESI Dottorato CD-ROM/202
Lingua di pubblicazione	Inglese
Formato	Risorsa elettronica
Livello bibliografico	Monografia

2. Record Nr. UNINA9910165020803321

Autore	McCarthy John <1966->
Titolo	So all can learn : a practical guide to differentiation / / John McCarthy
Pubbl/distr/stampa	Lanham, Maryland : , : Rowman & Littlefield, , 2017 ©2017
ISBN	1-4758-2572-2
Descrizione fisica	1 online resource (202 pages)
Disciplina	371.39/4
Soggetti	Individualized instruction
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	What is differentiation, really? -- Differentiation can be done well -- Assessments matter: making learning specific and realistic -- Informative assessments for the whole learner -- The truth about

		differentiated instruction -- Learner voice matters -- Differentiation in practice: readiness for all -- Differentiation in practice: interests for all -- Differentiation in practice: learning preferences for all.
3.	Record Nr.	UNINA9910484665003321
	Autore	Zuo Zongyu
	Titolo	Fixed-Time Cooperative Control of Multi-Agent Systems / / by Zongyu Zuo, Qing-Long Han, Boda Ning
	Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2019
	ISBN	3-030-20279-8
	Edizione	[1st ed. 2019.]
	Descrizione fisica	1 online resource (162 pages)
	Disciplina	006.30285436 006.3
	Soggetti	Automatic control Electrical engineering System theory Robotics Automation Mathematical optimization Control and Systems Theory Communications Engineering, Networks Systems Theory, Control Robotics and Automation Optimization
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
	Nota di contenuto	Introduction -- Fixed-Time Stability and Stabilization -- Fixed-Time Cooperative Control for First-Order Multi-Agent Systems -- Fixed-Time Cooperative Control for Second-Order Multi-Agent Systems -- Fixed-Time Cooperative Control for High-Order Multi-Agent Systems -- Fixed-Time Cooperative Control for Nonholonomic Chained-Form Multi-Agent Systems -- Distributed Optimization: And Edge-Based

Fixed-Time Consensus Approach -- Distributed Optimization With Preserved Network Connectivity.

Sommario/riassunto

This monograph presents new theories and methods for fixed-time cooperative control of multi-agent systems. Fundamental concepts of fixed-time stability and stabilization are introduced with insightful understanding. This book presents solutions for several problems of fixed-time cooperative control using systematic design methods. The book compares fixed-time cooperative control with asymptotic cooperative control, demonstrating how the former can achieve better closed-loop performance and disturbance rejection properties. It also discusses the differences from finite-time control, and shows how fixed-time cooperative control can produce the faster rate of convergence and provide an explicit estimate of the settling time independent of initial conditions. This monograph presents multiple applications of fixed-time control schemes, including to distributed optimization of multi-agent systems, making it useful to students, researchers and engineers alike.