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   Autore   Feyel Philippe

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   Sommario/riassunto   In the automotive industry, a Control Engineer must design a unique
   control law that is then tested and validated on a single prototype with
   a level of reliability high enough to to meet a number of complex
   specifications on various systems. In order to do this, the Engineer uses
   an experimental iterative process (Trial and Error phase) which relies
   heavily on his or her experience. This book looks to optimise the
   methods for synthesising servo controllers ny making them more direct
   and thus quicker to design. This is achieved by calculating a final
   controller to directly tackle the high-end system specs.