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Titolo	Locomotion and mechanics // Kevin McCombs
Pubbl/distr/stampa	New York : , : Cavendish Square, , 2017 2017
ISBN	1-5026-1942-3
Edizione	[First edition.]
Descrizione fisica	1 online resource (128 pages) : color illustrations
Collana	Robotics
Disciplina	629.8/92
Soggetti	Robotics Robots - Design and construction Robots - Motion
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Includes index.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	What is a robot made of? -- Understanding constraints -- Basic machines and power systems -- Problem solving with robotics -- The motion of humanoid robots.
Sommario/riassunto	This book describes the physical elements, such as gears, wheels, and belts, needed for the robot to maneuver around and over objects in its environment. Included is a section on how design can affect the performance of the robot.