1. Record Nr.   UNINA9910146067803321

   Titolo   Understanding craniofacial anomalies : the etiopathogenesis of craniosynostoses and facial clefting

   Pubbl/distr/stampa   [Place of publication not identified], : Wiley Liss, 2002

   ISBN   1-280-55634-X
                     9786610556342
                     0-471-46115-6
                     0-471-22195-3

   Descrizione fisica   1 online resource (585 pages)

   Disciplina   617.52

   Soggetti   Cleft Palate
                     Craniosynostoses
                     Craniofacial Abnormalities
                     Synostosis
                     Jaw Abnormalities
                     Plagiocephaly
                     Musculoskeletal Abnormalities
                     Mouth Abnormalities
                     Maxillofacial Abnormalities
                     Musculoskeletal Diseases
                     Dysostoses
                     Mouth Diseases
                     Jaw Diseases
                     Stomatognathic System Abnormalities
                     Congenital Abnormalities
                     Stomatognathic Diseases
                     Congenital, Hereditary, and Neonatal Diseases and Abnormalities
                     Diseases
                     Bone Diseases, Developmental
                     Bone Diseases
                     Surgery - General and By Type
                     Surgery & Anesthesiology
                     Health & Biological Sciences
                     Electronic books.

Lingua di pubblicazione	Inglese	
Formato	Materiale a stampa	
Livello bibliografico	Monografia	
Note generali	Bibliographic Level Mode of Issuance: Monograph	
Sommario/riassunto	This comprehensive textbook, edited by world-renowned experts in the field, provides answers to challenges in the diagnosis and treatment of craniofacial anomalies.The book integrates basic science and clinical perspectives, creating a more unified and practical "patient centered" approach. Organized in a logical, easy-to-follow structure, this reference reviews and presents cutting-edge findings, covering the state of the art in craniosynostosis and facial clefting from molecular, genetic, cellular, tissue, organismic, and populations levels. Using standardized nomenclature and consistent terminology, Understanding Craniofacial Anomalies incorporates the recent explosion of growth in studying genetic and epigenetic etiologies of syndromes, thereby providing a unique and holistic review of this important topic.	

2.	Record Nr.	UNINA9910145423003321
	Titolo	Fraud casebook [[electronic resource]] : lessons from the bad side of business / / edited by Joseph T. Wells
	Pubbl/distr/stampa	Hoboken, N.J., : John Wiley & Sons, c2007
	ISBN	1-119-19663-9
		1-281-22151-1
		9786611221515
		0-470-17867-1
	Descrizione fisica	1 online resource (626 p.)
	Altri autori (Persone)	WellsJoseph T
	Disciplina	363.25/963
		363.25963
	Soggetti	Fraud
		Electronic books.
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
	Note generali	Includes index.

Nota di contenuto	High art, low value ? how a connoisseur became a convict / Ellen Fischer -- The ambitious payroll manager / John Tonsick -- The insider / Craig R. Sinnamon -- Aloha, Hawaii! / Dominic A. D'Orazio -- What about Pete? / Michael Goldman -- Check, please / Peter Parillo -- The MoJo skim twins / John F. Kronick -- The mole / Manuel Pereira -- Her passion for fashion / Bethmara Kessler -- An unaffordable complex / Jeff Barsky -- A taxing problem / Andrew H. Kautz -- Phantom links in the supply chain / Christopher J. Kelly -- The trusting business owner / David Glusman -- The thirteen million dollar man / John Francolla -- They didn't know Jack / Janet McHard.
Sommario/riassunto	Praise for Fraud Casebook Lessons from the Bad Side of Business""I have known Mr. Wells for over twenty years. In my opinion, no one in the world knows more about fraud than he does.""-W. Steve Albrecht, Associate Dean, Marriott School of ManagementBrigham Young University, Provo, Utah""This book covers the entire range of fraud that can be encountered in the workplace.""-Grant D. Ashley, Vice President for Corporate Security and SurveillanceHarrah's Entertainment Inc., Las Vegas, Nevada""I had the pleasure of serving with Mr. Wells when both of us were voluntee

3.

Record Nr.	UNINA9910410652703321
Autore	Liu Yunhui
Titolo	Biologically inspired robotics / / edited by Yunhui Liu and Dong Sun
Pubbl/distr/stampa	Boca Raton, Fla., : CRC Press, c2012
	Boca Raton, Fla. : , : CRC Press, , 2012
ISBN	9786613526151
	9781315217314
	1315217317
	9780367381783
	0367381788
	9781280122293
	1280122293
	9781439854976
	1439854971
Edizione	[1st edition]
Descrizione fisica	1 online resource (xv, 324 p.) : ill
Classificazione	MED009000TEC007000TEC016000
Altri autori (Persone)	LiuYunhui
	SunDong <1967->
Disciplina	629.8/92
Soggetti	Robotics
	Bionics
	Biomimicry
	Biomechanics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Introduction to Biologically Inspired Robotics; Yunhui Liu and Dong Sun CPG-Based Control of Serpentine Locomotion of a Snake-Like Robot; Xiaodong Wu and Shugen Ma Analysis and Design of a Bionic Fitness Cycle; Jun Zhang, Ying Hu, Jianwei Zhang, Haiyang Jin, and Zhijian Long Human-Inspired Hyperdynamic Manipulation; Aiguo Ming and Chunquan Xu A School of Robotic Fish for Pollution Detection in Port; Huosheng Hu, John Oyekan, and Dongbing Gu Development of a Low-Noise Bio-Inspired Humanoid Robot Neck; Bingtuan Gao, Ning Xi, Jianguo Zhao, and Jing Xu Automatic Single-Cell Transfer Module; Huseyin Uvet, Akiyuki Hasegawa, Kenichi Ohara, Tomohito Takubo,

Yasushi Mae, and Tatsuo Arai Biomechanical Characterization of Human Red Blood Cells with Optical Tweezers; Youhua Tan, Dong Sun, and Wenhao Huang Nanorobotic Manipulation for a Single Biological Cell; Toshio Fukuda, Masahiro Nakajima, and Mohd Ridzuan Ahmad Measurement of Brain Activity Using Optical and Electrical Methods ; Atsushi Saito, Alexsandr Ianov, and Yoshiyuki Sankai Bowel Polyp Detection in Capsule Endoscopy Images with Color and Shape Features; Baopu Li and Max Q.-H. Meng Classification of Hand Motion Using Surface EMG Signals; Xueyan Tang, Yunhui Liu, Congyi Lu, and Weilun Poon Multifunctional Actuators Utilizing Magnetorheological Fluids for Assistive Knee Braces; H. T. Guo and W. H. Liao Mathematical Modeling of Brain Circuitry during Cerebellar Movement Control; Henrik Jorntell, Per-Ola Forsberg, Fredrik Bengtsson, and Rolf Johansson Development of Hand Rehabilitation System Using Wire-Driven Link Mechanism for Paralysis Patients; Hiroshi Yamaura1, Kojiro Matsushita, Ryu Kato, and Hiroshi Yokoi A Test Environment for Studying the Human-Likeness of Robotic Eye Movements Index

| Sommario/riassunto | Biologically inspired robotics is an interdisciplinary subject between robotics and biology that involves how to apply biological ideas and phenomena to engineering problems in robotics (biomimetics), and how to apply robotics technology to understanding of biological systems and their behaviors (bio-robotic modeling/analysis). The efforts in biologically inspired robotics are not just restricted to research work in laboratories, their novel applications are also being extensively explored in services, education, rehabilitation, medical care and other sectors. The objective of this book is to introduce the latest efforts in research of biologically inspired robotics, covering both biomimetics (with chapters in biologically inspired robot design and control, bio-sensing, bio-actuation, and micro/nano bio-robotic systems) and bio-robotic modeling/analysis (discussing human hand motion recognition using biological signals, modeling of human brain activities, characterization of cell properties using robotic systems). In order to provide readers a better understanding on organization of this book, the content is classified into four parts: (1) biologically inspired robot design and control, (2) micro/nano bio-robotic systems, (3) biological measurement and actuation, and (4) applications of robotics technology to biological problems-- |