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| Articulated Motion and Deformable Objects : Third International Workshop, AMDO 2004, Palma de Mallorca, Spain, September 22-24, 2004, Proceedings / / edited by Francisco J. Perales, Bruce A. Draper |
| Berlin, Heidelberg : , : Springer Berlin Heidelberg : , : Imprint : Springer, , 2004 |
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| Application software |
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| Using a Generalized Linear Mixed Model to Study the Configuration Space of a PCA+LDA Human Face Recognition Algorithm Discrete Techniques for Real-Time Inspection and Interaction in Virtual Reality Progress in Sign and Gesture Recognition A Haptic Sculpting Technique Based on Volumetric Representation Adaptation of Mesh Morphing Techniques for Avatars Used in Web Applications Improvement of Modal Matching Image Objects in Dynamic Pedobarography Using Optimization Techniques Ear Biometrics Based on Geometrical Method of Feature Extraction A Probabilistic |
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| | Framework for Articulated Shape Recognition Neuroanatomy Registration: An Algebraic-Topology Based Approach Recognition and Tracking of the Members of a Moving Human Body Image Cues Fusion for Object Tracking Based on Particle Filter 3D Human Walking Modeling Variant Design in Immersive Virtual Reality: A Markup Language for Scalable CSG Parts Application of Repeated GA to Deformable Template Matching in Cattle Images On-the-Fly Training Deformable Object Matching Based on Multi-scale Local Histograms Detecting Human Heads and Face Orientations Under Dynamic Environment Analysis of Human Walking Based on aSpaces Complex Articulated Object Tracking 2D Human Tracking by Efficient Model Fitting Using a Path Relinking Particle Filter Multiple Facial Feature Tracking Using Multi-cue Based Prediction Model A System for Choreographic Simulation of Ballet Using a 3D Motion Archive on the Web Human Body Analysis with Biomechanics Criteria A Comparison of Algorithm Design Paradigms in Active Contours for Muscle Recognition Real Time Segmentation and Tracking of Face and Hands in VR Applications. |
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| Sommario/riassunto | The AMDO 2004 workshop took place at the Universitat de les Illes Balears (UIB) on 22–24 September, 2004, institutionally sponsored by the International Association for Pattern Recognition (IAPR), the MCYT (Comision Interm- isterial de Ciencia y Tecnologia, Spanish Government), the AERFAI (Spanish Association for Pattern Recognition and Image Analysis), the EG (Eurogra- ics Association) and the Mathematics and Computer Science Department of the UIB. Also important commercial sponsors collaborated with practical dem- strations; the main contributors were: Barco Electronics Systems (Title Sp- sor), VICOM Tech, ANDROME Iberica, CESA and TAGrv. The subject of the workshop was ongoing research in articulated motion on a sequence of images and sophisticated models for deformable objects. The goals of these areas are to understand and interpret the motion of complex objects that can be found in sequences of images in the real world. The main topics considered priorities are: deformable models, motion analysis, articulated models and animation, visualization of deformable models, 3D recovery from motion, single or multiple human motion analysis and synthesis, applications of deformable models and motion analysis, face tracking, recovery and recognition models, and virtual and augmented reality systems. |