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5.2 Continuous Nonlinearities5.2.1 Engine Fuel Control System Example; 5.3 Discontinuous Nonlinearities; 5.3.1 Stability Analysis with Discontinuous Nonlinearities; 5.4 The Transport Delay; 5.5 Simulation; 5.6 Chapter Summary; 6 Electronic Controls; 6.1 Analog Electronic Controls; 6.1.1 The Operational Amplifier; 6.1.2 Building Analog Control Algorithms; 6.2 The Digital Computer as a Dynamic Control Element; 6.2.1 Signal Conversion; 6.2.2 Digital Controller Architectures; 6.3 The Stability Impact of Digital Controls; 6.4 Digital Control Design Example; 6.5 Creating Digital Control Algorithms
6.5.1 The Integrator

Sommario/riassunto

In the current climate of increasing complexity and functional integration in all areas of engineering and technology, stability and control are becoming essential ingredients of engineering knowledge. Many of today's products contain multiple engineering technologies, and what were once simple mechanical, hydraulic or pneumatic products now contain integrated electronics and sensors. Control theory reduces these widely varied technical components into their important dynamic characteristics, expressed as transfer functions, from which the subtleties of dynamic behaviours can be analyzed and u