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4.6 Robust Learning Algorithms

Sommario/riassunto

A highly accessible and unified approach to the design and analysis of intelligent control systemsAdaptive Approximation Based Control is a tool every control designer should have in his or her control toolbox. Mixing approximation theory, parameter estimation, and feedback control, this book presents a unified approach designed to enable readers to apply adaptive approximation based control to existing systems, and, more importantly, to gain enough intuition and understanding to manipulate and combine it with other control tools for applications that have not been encountered b