

1. Record Nr.	UNINA9910141726103321
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Titolo	Object detection and recognition in digital images [[electronic resource]] : theory and practice // Bogusaw Cyganek
Pubbl/distr/stampa	Chichester, West Sussex, U.K., : John Wiley & Sons, Inc., 2013
ISBN	1-118-61836-X 1-118-61838-6 1-118-61837-8
Descrizione fisica	1 online resource (552 p.)
Disciplina	621.39/94
Soggetti	Pattern recognition systems Image processing - Digital techniques Computer vision
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	OBJECT DETECTION AND RECOGNITION IN DIGITAL IMAGES; Contents; Preface; Acknowledgements; Notations and Abbreviations; 1 Introduction; 1.1 A Sample of Computer Vision; 1.2 Overview of Book Contents; References; 2 Tensor Methods in Computer Vision; 2.1 Abstract; 2.2 Tensor - A Mathematical Object; 2.2.1 Main Properties of Linear Spaces; 2.2.2 Concept of a Tensor; 2.3 Tensor - A Data Object; 2.4 Basic Properties of Tensors; 2.4.1 Notation of Tensor Indices and Components; 2.4.2 Tensor Products; 2.5 Tensor Distance Measures; 2.5.1 Overview of Tensor Distances 2.5.1.1 Computation of Matrix Exponent and Logarithm Functions 2.5.2 Euclidean Image Distance and Standardizing Transform; 2.6 Filtering of Tensor Fields; 2.6.1 Order Statistic Filtering of Tensor Data; 2.6.2 Anisotropic Diffusion Filtering; 2.6.3 IMPLEMENTATION of Diffusion Processes; 2.7 Looking into Images with the Structural Tensor; 2.7.1 Structural Tensor in Two-Dimensional Image Space; 2.7.2 Spatio-Temporal Structural Tensor; 2.7.3 Multichannel and Scale-Space Structural Tensor; 2.7.4 Extended Structural Tensor; 2.7.4.1 IMPLEMENTATION of the Linear and Nonlinear Structural Tensor 2.8 Object Representation with Tensor of Inertia and Moments 2.8.1

IMPLEMENTATION of Moments and their Invariants; 2.9 Eigendecomposition and Representation of Tensors; 2.10 Tensor Invariants; 2.11 Geometry of Multiple Views: The Multifocal Tensor; 2.12 Multilinear Tensor Methods; 2.12.1 Basic Concepts of Multilinear Algebra; 2.12.1.1 Tensor Flattening; 2.12.1.2 IMPLEMENTATION Tensor Representation; 2.12.1.3 The k-mode Product of a Tensor and a Matrix; 2.12.1.4 Ranks of a Tensor; 2.12.1.5 IMPLEMENTATION of Basic Operations on Tensors; 2.12.2 Higher-Order Singular Value Decomposition (HOSVD) 2.12.3 Computation of the HOSVD 2.12.3.1 Implementation of the HOSVD Decomposition; 2.12.4 HOSVD Induced Bases; 2.12.5 Tensor Best Rank-1 Approximation; 2.12.6 Rank-1 Decomposition of Tensors; 2.12.7 Best Rank-(R1, R2, . . . , RP) Approximation; 2.12.8 Computation of the Best Rank-(R1, R2, . . . , RP) Approximations; 2.12.8.1 IMPLEMENTATION - Rank Tensor Decompositions; 2.12.8.2 CASE STUDY - Data Dimensionality Reduction; 2.12.9 Subspace Data Representation; 2.12.10 Nonnegative Matrix Factorization; 2.12.11 Computation of the Nonnegative Matrix Factorization 2.12.12 Image Representation with NMF 2.12.13 Implementation of the Nonnegative Matrix Factorization; 2.12.14 Nonnegative Tensor Factorization; 2.12.15 Multilinear Methods of Object Recognition; 2.13 Closure; 2.13.1 Chapter Summary; 2.13.2 Further Reading; 2.13.3 Problems and Exercises; References; 3 Classification Methods and Algorithms; 3.1 Abstract; 3.2 Classification Framework; 3.2.1 IMPLEMENTATION Computer Representation of Features; 3.3 Subspace Methods for Object Recognition; 3.3.1 Principal Component Analysis; 3.3.1.1 Computation of the PCA 3.3.1.2 PCA for Multi-Channel Image Processing

Sommario/riassunto

Object detection, tracking and recognition in images are key problems in computer vision. This book provides the reader with a balanced treatment between the theory and practice of selected methods in these areas to make the book accessible to a range of researchers, engineers, developers and postgraduate students working in computer vision and related fields. Key features: Explains the main theoretical ideas behind each method (which are augmented with a rigorous mathematical derivation of the formulas), their implementation (in C++) and demonstrated working in real applications.
