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	Nota di contenuto	Preface Part One Basics of Process Dynamics 1 Mathematical Representations of Linear Processes 1.1 Introduction to Process Control and Identification 1.2 Properties of Linear Processes 1.3 Laplace Transform 1.4 Transfer Function and State-Space Systems Problems 2 Simulations 2.1 Simulating Processes Composed of Differential Equations 2.2 Simulating Processes Including Time Delay 2.3 Simulating Closed-Loop Control Systems 2.4 Useful Numerical Analysis Methods Problems 3 Dynamic Behavior of Linear Processes 3.1 Low-Order Plus Time- Delay Processes 3.2 Process Reaction Curve Method 3.3 Poles and Zeroes 3.4 Block Diagram 3.5 Frequency Responses Problems Part Two Process Control 4 Proportional-Integral-Derivative Control 4.1 Structure of Proportional-Integral-Derivative Controllers and Implementation in Computers/Microprocessors 4.2 Roles of Three Parts of Proportional-Integral-Derivative Controllers 4.3 Integral Windup 4.4 Commercial Proportional-Integral-Derivative

	Controllers Problems 5 Proportional-Integral-Derivative Controller Tuning 5.1 Trial-and-Error Tuning 5.2 Simple Process Identification Methods 5.3 Ziegler-Nichols Tuning Rule 5.4 Internal Model Control Tuning Rule 5.5 Integral of the Time- Weighted Absolute Value of the Error Tunning Rule for a Second-Order Plus Time-Delay Model (ITAE-1) 5.6 Integral of the Time-Weighted Absolute Value of the Error Tunning Rule for a Second-Order Plus Time-Delay Model (ITAE-2) 5.7 Optimal Gain Margin Tuning Rule for an Unstable Second-Order Plus Time-Delay Model (OGM-unstable) 5.8 Model Reduction Method for Proportional-Integral-Derivative Controller Tuning 5.9 Consideration of Modeling Errors 5.10 Concluding Remarks Problems 6 Dynamic Behavior of Closed- Loop Control Systems 6.1 Closed-Loop Transfer Function and Characteristic Equation 6.2 Bode Stability Criterion 6.3 Nyquist Stability Criterion. 6.4 Gain Margin and Phase Margin Problems 7 Enhanced Control Strategies 7.1 Cascade Control 7.2 Time-Delay Compensators 7.3 Gain Scheduling 7.4 Proportional-Integral- Derivative Control using Internal Feedback Loop Problems Part Three Process Identification 8 Process Identification Methods for Frequency Response Models 8.1 Fourier Series 8.2 Frequency Response Analysis and Autotuning 8.3 Describing Function Analysis 8.4 Fourier Analysis 8.5 Modified Fourier Transform 8.6 Frequency Response Analysis with Integrals Problems 9 Process Identification Methods for Discrete-Time Difference Equation Models 9.1 Identification Method Problems 10 Process Identification Methods for Discrete-Time Difference Equation Models 10.1 Prediction Error Identification Method for the Output Error Model 10.3 Prediction Error Identification Method Problems 10 Process Identification Method for the Output Error Model 10.4 Concluding Remarks Problems 11 Model Conversion from Discrete-Time to Continuous-Time Linear Models
Commonia (dia seconda	A.1 Setup of the Virtual Control System A.2 Examples Index.
Sommano/flassunto	to understand the essential concepts of feedback control, process identification, autotuning, and design of real feedback controllers, especially PID controllers. Sung, Lee, and Lee introduce the fundamentals of process control and dynamics, analysis tools (Bode plot, Nyquist plot), PID controllers and tuning, controller designs, along with the advances control strategies which have been widely used in industry. Included are numerous numerical examples and MATLAB codes to aid the reader in solving real problems. Readers will be able to design their own controllers, implement them, and confirm performance in real-time using real-time virtual processes. Combines the basics with recent research, helping the novice grasp advanced

topics Brings several industrially important topics together: . Finishing topics with implementation codes. Process identification and implementation. PID controller tuning and implementation. Enhanced control strategies and implementation Includes all source codes and real-time virtual processes for self-practice and modeling/controller design courses Contains problems at the end of every chapter Written by a team of recognized experts in the area Process Identification and PID Control is ideal for undergraduate and graduate students in process control, advanced process control, and process identification. Practicing control engineers and R&D personnel in refineries and chemical plants will find this book to be a key reference. Professionals in industry in particular will appreciate the techniques for developing process identification and control software, as well as implementing microprocessor controllers. Source code for readers and course supplements for instructors available at <a href="http://www.wiley. com/go/swsung">www.wiley.com/go/swsung</a>.