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Nota di contenuto	MODEL-BASED VISUALTRACKING: The OpenTL Framework; CONTENTS; PREFACE; CHAPTER 1: INTRODUCTION; CHAPTER 2: MODEL REPRESENTATION; CHAPTER 3: THE VISUAL MODALITY ABSTRACTION; CHAPTER 4: EXAMPLES OF VISUAL MODALITIES; CHAPTER 5: RECURSIVE STATE-SPACE ESTIMATION; CHAPTER 6: EXAMPLES OF TARGET DETECTORS; CHAPTER 7: BUILDING APPLICATIONS WITH OpenTL; APPENDIX A: POSE ESTIMATION; APPENDIX B: POSE REPRESENTATION; NOMENCLATURE; BIBLIOGRAPHY; INDEX; Color plates
Sommario/riassunto	This book has two main goals: to provide a unified and structured overview of this growing field, as well as to propose a corresponding software framework, the OpenTL library, developed by the author and his working group at TUM-Informatik. The main objective of this work is to show, how most real-world application scenarios can be naturally cast into a common description vocabulary, and therefore implemented and tested in a fully modular and scalable way, through the definition of a layered, object-oriented software architecture. The resulting architecture covers in a seamless way all processi

