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Sommario/riassunto	Nature has always been a source of inspiration and ideas for the robotics community. New solutions and technologies are required and hence this book is coming out to address and deal with the main challenges facing walking and climbing robots, and contributes with innovative solutions, designs, technologies and techniques. This book reports on the state of the art research and development findings and results. The content of the book has been structured into 5 technical research sections with total of 30 chapters written by well recognized researchers worldwide.