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   Nota di contenuto   Some backgrounds -- Stabilization of second order evolution equations
                       by a class of unbounded feedbacks -- Stabilization of second order
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                       behaviour of concrete dissipative systems -- Systems with delay --
                       Bibliography.

   Sommario/riassunto By introducing a new stabilization methodology, this book
                       characterizes the stability of a certain class of systems. The stability
                       (exponential, polynomial, or weaker) for the closed loop problem is
                       reduced to an observability estimate for the corresponding
                       uncontrolled system combined with a boundedness property of the
                       transfer function of the associated open loop system. A similar strategy
                       is applied to systems where a delay term is added. The book concludes
                       with many concrete examples. This book is addressed to graduate
                       students in mathematics or engineering and also to researchers with an
                       interest in stabilization and control systems governed by partial
                       differential equations.