

1. Record Nr.	UNINA990009611950403321
Autore	Istituto geografico militare
Titolo	Ramacca [Documento cartografico] / IGM
Pubbl/distr/stampa	Firenze : IGM, 1958
Edizione	[2. ed]
Descrizione fisica	1 carta ; 37 x 42 cm su foglio 51 x 62 cm
Collana	Carta d'Italia ; 269, quadrante 3, tavoletta SE
Localione	ILFGE
Collocazione	MP Cass.2 269, 3(2)
Lingua di pubblicazione	Italiano
Formato	Materiale cartografico a stampa
Livello bibliografico	Monografia
Note generali	Il meridiano di riferimento è Monte Mario, Roma Rilievo del 1940

2. Record Nr.	UNINA9910299494103321
Autore	Angeles Jorge
Titolo	Fundamentals of Robotic Mechanical Systems : Theory, Methods, and Algorithms / / by Jorge Angeles
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2014
ISBN	3-319-01851-5
Edizione	[4th ed. 2014.]
Descrizione fisica	1 online resource (XXIII, 589 p. 160 illus., 18 illus. in color.)
Collana	Mechanical Engineering Series, , 0941-5122 ; ; 124
Disciplina	629.892
Soggetti	Mechanical engineering Robotics Automation Mechanical Engineering Robotics and Automation
Lingua di pubblicazione	Inglese
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Nota di contenuto	An Overview of Robotic Mechanical Systems -- Mathematical Background -- Fundamentals of Rigid-Body Mechanics -- Geometry of Decoupled Serial Robots -- Kinetostatics of Serial Robots -- Trajectory Planning: Pick-and-Place Operations -- Dynamics of Serial Robotic Manipulators -- Special Topics in Rigid-Body Kinematics -- Geometry of General Serial Robots -- Kinematics of Alternative Robotic Mechanical Systems -- Trajectory Planning: Continuous-Path Operations -- Dynamics of Complete Robotic Mechanical Systems -- Kinematics of Rotations: A Summary -- Numerical Equation-Solving.
Sommario/riassunto	The 4th edition includes updated and additional examples and exercises on the core fundamental concepts of mechanics, robots, and kinematics of serial robots. New images of CAD models and physical robots help to motivate concepts being introduced. Each chapter of the book can be read independetly of others as it addresses a separate issue in robotics.