

1.	Record Nr.	UNINA990006472760403321
	Autore	Cohen, Barry
	Titolo	L'Afrique australe de Kissinger a Carter / Barry Cohen, Howard Schissel
	Pubbl/distr/stampa	Paris : Harmattan, 1977
	Descrizione fisica	192 p. ; 22 cm
	Disciplina	968
	Locazione	FSPBC
	Collocazione	XIV E 965
	Lingua di pubblicazione	Italiano
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
2.	Record Nr.	UNISA990003086940203316
	Autore	ANACLERIO, Mario
	Titolo	Internal auditing : dalla teoria alla pratica / Mario Anaclerio, Angelo Miglietta, Simone Squaiella
	Pubbl/distr/stampa	Milanofiori, Assago : Ipsoa, 2007
	ISBN	978-88-217-2597-5
	Descrizione fisica	337 p. ; 24 cm + 1 cd-rom
	Collana	Metodi e strumenti
	Altri autori (Persone)	MIGLIETTA, Angelo SQUAIELLA, Simone
	Disciplina	657.155
	Soggetti	Aziende - Rischi - Gestione
	Collocazione	657.155 ANA 1 (IRA 26 158)
	Lingua di pubblicazione	Italiano
	Formato	Materiale a stampa
	Livello bibliografico	Monografia

3. Record Nr.	UNINA9910999667003321
Autore	Cardone Mauro
Titolo	Automated and Autonomous Navigation Powered by GNSS : Navigation Techniques and Applications, Future Automated Navigation / / by Mauro Cardone
Pubbl/distr/stampa	Cham : , : Springer Nature Switzerland : , : Imprint : Springer, , 2025
ISBN	3-031-78753-6
Edizione	[1st ed. 2025.]
Descrizione fisica	1 online resource (XL, 293 p. 38 illus., 37 illus. in color.)
Disciplina	620
Soggetti	Vehicles Automatic control Robotics Automation Transportation engineering Traffic engineering Vehicle Engineering Control, Robotics, Automation Transportation Technology and Traffic Engineering
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Part 1. Navigation techniques -- Chapter 1. Multisensor fusion -- Chapter 2. RAIM algorithm -- Chapter 3. Multi-Level integrity control -- Chapter 4. Machine learning and deep learning -- Chapter 5. Robust navigation -- Chapter 6. Cooperative navigation -- Part 2. Navigation Applications -- Chapter 7. Automatic train protection with GNSS -- Chapter 8. Automatic road navigation -- Chapter 9. Autonomous maritime navigation -- Chapter 10. Autonomous aerial navigation...Etc.
Sommario/riassunto	This book is the result of one-year investigation in all the available technologies necessary to build an efficient navigation system usable on rovers moving on the ground and at the sea, centered on GNSS (Global Navigation Satellite System). It is used as instruction note for the calls for tender in the Italian Space Agency. It targets the applications of automated and autonomous navigation for the following

types of rover: trains at level 2 of ERTMS/ETCS—autonomous cars, starting from level 3 of SAE -MASS (Maritime Autonomous Surface Ships) at level 4 of IMO. The material is already edited for the using of professionals and engineers who need to build a navigation system on top of COTS hardware. The topics cover in a thorough view all the necessary subjects to build an efficient positioning system for the rover enabling coping with all kind of environments and all interferences and always warranting a minimum level of the positioning KPIs (reliability, availability, integrity, and accuracy). The localization system built according to these guidelines will be ready to be certified and the product will be at TRL 6 (i.e., technology demonstrated in the relevant environment).
