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| 1. Record Nr. | UNINA990004156080403321 |
| Autore | Augustus, Gaius Iulius Caesar Octavianus <63 a.C.-14> |
| Titolo | Caesaris Augusti Index rerum a se gestarum sive monumentum ancyranum / ex reliquiis graecae interpretationis restituit Ioannes Franzius ; commentario perpetuo instruxit A.W. Zumptius |
| Pubbl/distr/stampa | Berolini, : Ex Libraria G. Reimeri, 1845 |
| Descrizione fisica | 120 p. tav. ; 29 cm |
| Locazione | FLFBC |
| Collocazione | XIV B 132 |
| Lingua di pubblicazione | Latino |
| Formato | Materiale a stampa |
| Livello bibliografico | Monografia |
| 2. Record Nr. | UNINA9910585941003321 |
| Autore | Suarez Alejandro |
| Titolo | Aerial Robotics for Inspection and Maintenance |
| Pubbl/distr/stampa | Basel, : MDPI - Multidisciplinary Digital Publishing Institute, 2022 |
| Descrizione fisica | 1 online resource (218 p.) |
| Soggetti | History of engineering & technology
Technology: general issues |
| Lingua di pubblicazione | Inglese |
| Formato | Materiale a stampa |
| Livello bibliografico | Monografia |
| Sommario/riassunto | Aerial robots with perception, navigation, and manipulation capabilities are extending the range of applications of drones, allowing the integration of different sensor devices and robotic manipulators to perform inspection and maintenance operations on infrastructures such |

as power lines, bridges, viaducts, or walls, involving typically physical interactions on flight. New research and technological challenges arise from applications demanding the benefits of aerial robots, particularly in outdoor environments. This book collects eleven papers from different research groups from Spain, Croatia, Italy, Japan, the USA, the Netherlands, and Denmark, focused on the design, development, and experimental validation of methods and technologies for inspection and maintenance using aerial robots.
