1. Record Nr. UNICASRML0310323

Autore	Brown, Tony
Titolo	The environment and aggregate-related archaeology / Tony Brown [A.G Brown BSc PhD FGS FSA]
Pubbl/distr/stampa	Norfolk, : Heritage marketing and publications - Oxford, : Oxbow Books, ©2009
Descrizione fisica	X, 220 p. : ill., mappe ; 30 cm
Disciplina	930.10283
Soggetti	Archeologia ambientale - Gran Bretagna Scavi archeologici - Gran Bretagna
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	In calce al front.: University of Southampton, School of Geography; English Heritage. -P. 201-213: riferimenti bibliografici e indici

2. Record Nr. UNINA9910921016303321

Autore	Berns Karsten
Titolo	Walking Robots into Real World : Proceedings of the CLAWAR 2024 Conference, Volume 2 / / edited by Karsten Berns, Mohammad Osman Tokhi, Arne Roennau, Manuel F. Silva, Rüdiger Dillmann
Pubbl/distr/stampa	Cham : , : Springer Nature Switzerland : , : Imprint : Springer, , 2024
ISBN	9783031713019 303171301X
Edizione	[1st ed. 2024.]
Descrizione fisica	1 online resource (330 pages)
Collana	Lecture Notes in Networks and Systems, , 2367-3389 ; ; 1115
Altri autori (Persone)	TokhiMohammad Osman RoennauArne SilvaManuel F DillmannRüdiger
Disciplina	629.8932
Soggetti	Automatic control Robotics Automation Computational intelligence Control, Robotics, Automation Computational Intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Verification of decreasing bearing capacity while imparting vibration to ground in DEM simulation for underground moving robots -- Intelligent PID Controller for Vibration Suppression of Horizontal Flexible Plate Based on Social Spider Optimization -- Efficient Stream Based Active Learning Initialization for Legged Robots based on a PCAK Means Image Selection Approach -- Concept of Pneumatic Soft Robot Suction Driven Locomotion.
Sommario/riassunto	The book is also a good source for courses in robotics and automation, control engineering, mechanical engineering, and mechatronics. CLAWAR 2024 is the 27th International Conference Series on Climbing and Walking Robots and Mobile Machine Support Technologies. The conference is organized by CLAWAR Association in collaboration with

the RPTU Kaiserslautern-Landau and FZI Center for Information Technology, Germany, during September 4–6, 2024. CLAWAR 2024 provides the latest research and development findings and state-of-the-art insights into the mobile robotics and associated technologies in a diverse range of application scenarios, within the framework of “walking robots into real world.” The topics covered include AI-based systems and solutions, biologically inspired systems and solutions, human-like robots, innovative grippers, innovative robot design, planetary exploration, planning and control, prosthetics and rehabilitation, quadruped robots, and robotic applications. The intended readership includes participants of CLAWAR 2024 conference, worldwide researchers, scientists, and educators in the areas of robotics and related topics.